## **Useful Hypothesis in Inverse Problems of Interpretation**

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In this paper one possible approach to the statement of interpretation inverse problems and the justification of practical application of approximate solutions are proposed [1,2].

Let's present an inverse problem of interpretation as solution of equation

$$\widetilde{A}z = u_{\delta}, \tag{1}$$

where  $\tilde{A}$  is compact operator,  $u_{\delta}$  is initial data,  $z \in Z$ ,  $u_{\delta} \in U$  (Z, U are functional spaces with norm).

Further we shall believe that error of function  $u_{\delta}$  from the exact function  $u_{ex}$  has the given size  $\delta$ :

$$\left\| u_{\delta} - u_{ex} \right\|_{\chi} \le \delta \,. \tag{2}$$

In inverse problems of interpretation it is necessary to take into account the inaccuracy of operator  $\tilde{A}$  in relation to the exact operator  $A_{ex}$  additionally [1,3].

Let us suppose that the characteristic of an error of the operator  $\tilde{A}$  is given:

$$\left\| \widetilde{A} - A_{ex} \right\|_{Z \to U} \le h.$$
(3)

The set of possible solution of equation (1) is necessary to extend to set  $Q_{\delta,h}$  taking into account the inaccuracy of the operator  $\tilde{A}$ :

$$Q_{\delta,h} = \{ z : z \in \mathbb{Z}, \left\| \widetilde{A} z - u_{\delta} \right\|_{U} \le h \left\| z \right\|_{Z} + \delta \}.$$

The algorithm for the solution of the incorrect problem with approximate operator was proposed in work [4] which is based on Tikhonov's regularization method [5].

The statement of such interpretation inverse problem can be formulated as follows for obtaining of the stable solution: it is necessary to find an element  $z_{est} \in Q_{\delta,h}$  on which the greatest lower bound of some stabilizing functional  $\Omega[z]$  is reached

$$\inf_{z \in Q_{\delta,h} \cap Z_1} \Omega[z] = \Omega[z_{est}], \tag{4}$$

where  $Z_1$  is subset of Z, on subset  $Z_1$  has been defined stabilizing functional  $\Omega[z]$ , the set  $Z_1$  is everywhere dense in Z [5].

One of the important characteristics for the specified algorithm is the size h of an error. The definition of h represents significant difficulties, as the exact operator  $A_{ex}$  is unknown.

By result of the solution of interpretation inverse problem it is necessary to accept some approximation  $\tilde{z}$  to the exact solution  $z_{ex}$  of the equation (1) or its estimation  $z_{est}$  in the beforehand certain sense [1,2].

The functional  $\Omega[z]$  can characterize the chosen property of the exact solution (for example, smoothness). The approximated solution will give the estimation from below of exact solution on a degree of smoothness. If a functional  $\Omega[z]$  characterizes a deviation of the approximate solution from the given function  $z_{ap}$ , then the solution of an extreme problem (4) will give function from set  $Q_{\delta,h} \cap Z_1$  closest to function  $z_{ap}$ . Thus it is obvious that  $z_{ap}$  should not belong to set  $Q_{\delta,h} \cap Z_1$ .

The estimation of a deviation of the operator  $\tilde{A}$  from exact operator  $A_{ex}$  cannot be made essentially at a consideration of interpretation problems.

For overcoming the specified difficulties it is offered to accept the following *hypothesis*: for the exact solution  $z_{ex}$  of the equation  $A_{ex} z = u_{ex}$  the inequality is valid

$$\Omega[z_{ex}] \ge \Omega[\tilde{z}], \tag{4}$$

where  $\tilde{z}$  is regularized solution of equation (1) with approximate operator  $\tilde{A}$  and approximate initial data  $u_{\delta}$ ,  $\Omega[z]$  is stabilized functional [5].

The offered *hypothesis* don't use the size of inaccuracy h of the operator  $\tilde{A}$  from the exact operator  $A_{ex}$ , which cannot be defined essentially, at the solution of inverse problems of interpretation.

The satisfaction of an inequality (4) is obvious if the operators  $A_{ex}$ ,  $\tilde{A}$  are linear. For the nonlinear operator  $A_{ex}$  (that in the greater degree corresponds to a reality) the inequality (4) can be proved by properties of the approximated operators which are used in calculations [6].

Use of the offered hypothesis allows to receive various objective estimations of the exact solution  $z_{ex}$  of inverse problems such as (1) that is important in recognition problems [1,2]. Moreover the size h is not used in calculations. At  $\tilde{A} \rightarrow A_{ex}$  the estimation of function  $z_{ex}$  will be more exact. For definition of parameter regularization it is possible to use a usual discrepancy method [5] where the value h is absent.

Offered algorithm can be use also for estimation of real unknown parameters of physical process by identification method.

## References

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