

Stability Estimates and Convergent Numerical Method for Thermoacoustic Tomography with an Arbitrary Elliptic Operator

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All theorems below are only brief outlines of results: for brevity of this presentation. Detailed formulations can be found in the paper:

Inverse Problems, 29, 25014, 2013.

Inverse problem of thermoacoustic tomography

- In thermoacoustic tomography a short radio frequency pulse is sent in a biological tissue. Some energy is absorbed. Malignant lesions absorb more energy than healthy ones. Then the tissue expands and radiates a pressure wave.

Inverse Problem. Let $\Omega \subset \mathbb{R}^3$, $\partial\Omega \in C^4$ be a bounded domain, $Q_T = \partial\Omega \times (0, T)$, $S_T = \partial\Omega \times (0, T)$.

$$u_{tt} = c^2(x) \Delta u, x \in \mathbb{R}^3, t \in (0, T), \quad (1)$$

$$u(x, 0) = f(x), u_t(x, 0) = 0. \quad (2)$$

$$f(x) = 0, c(x) = 1, x \in \mathbb{R}^n \setminus \Omega. \quad (3)$$

Given the function $g(x, t)$,

$$u|_{S_T} = g(x, t), \quad (4)$$

find the initial condition $f(x)$.

Step 1 (elementary). Find the normal derivative at $h(x, t) = \partial_\nu u|_{S_T}$. Solve the initial boundary value problem

$$\begin{aligned}u_{tt} &= \Delta u, x \in \mathbb{R}^3 \setminus \Omega, t \in (0, T), \\u(x, 0) &= 0, u_t(x, 0) = 0, x \in \mathbb{R}^n \setminus \Omega, \\u &|_{S_T} = g(x, t).\end{aligned}$$

Hence,

$$\|h\|_{L_2(S_T)} \leq C \|g\|_{H^2(S_T)}. \quad (5)$$

1. Lipschitz stability via Carleman estimates for hyperbolic equations and inequalities.

Klibanov and Malinsky, 1991 (**the first result**); Kazemi and Klibanov, 1993; Klibanov and Timonov (book), 2004; Klibanov, 2005; Lasiecka, Triggiani and Zhang, 1999, 2004 (two papers; applications in the control theory); Isakov (book, 2006); Romanov 2006 (two papers); Clason and Klibanov, 2007; Klibanov, survey: "Carleman estimates for global uniqueness, stability and numerical methods for coefficient inverse problems", Journal of Inverse and Ill-Posed Problems, published online, 2013; preprint is available on arxiv.

Let $x_0 \in \Omega$,

$$(x - x_0, \nabla (c^{-2}(x))) \geq \alpha = \text{const.} > 0, \forall x \in \bar{\Omega}. \quad (6)$$

Particular case: $c(x) \equiv 1$. A slight modification of (6) implies non-trapping.

Hyperbolic inequality

$$\begin{aligned} |w_{tt} - c^2(x) \Delta w| &\leq A[|\nabla w| + |w_t| + |w| + |p|] \text{ in } Q_T, \quad (7) \\ w_t(x, 0) &= 0. \end{aligned}$$

Then

$$\|w\|_{H^1(Q_T)} \leq C \left[\|w|_{S_T}\|_{H^1(S_T)} + \|\partial_\nu w|_{S_T}\|_{L_2(S_T)} + \|p\|_{L_2(Q_T)} \right]. \quad (8)$$

The trace theorem (5) and (8) imply that for thermoacoustic tomography

$$\|f\|_{L^2(Q_T)} \leq C \|g\|_{H^2(S_T)}.$$

$T = T(c)$ is sufficiently large. In the case $c(x) \equiv 1$,
 $T > \text{diam}(\Omega)/2$.

2. Numerical Methods.

Quasi-Reversibility of Lattes and Lions (1969), convergence via Lipschitz stability: Klibanov and Malinsky, 1991 (theory). Numerics and convergence: Klibanov and Rakesh, 1992; Clason and Klibanov, 2007; Klibanov, Kuzhuget, Kabanikhin and Nechaev, 2008. Agranovsky and Kuchment, 2007.

3. Explicit reconstruction formulae for the case of the wave operator.

Good performance of numerical methods: Finch, Patch and Rakesh, 2004; Finch, Haltmeier and Rakesh, 2007; Kunyansky, 2008; Kunyansky and Kuchment, 2008 (survey). Good numerical performances.

- However, in all past publications some restrictive conditions were imposed on the function $c(x)$, e.g. (6).
- The case of a general elliptic operator $L(x)$ in $u_{tt} = L(x)u$ was not considered.
- Numerical methods for the case of a general elliptic operator $L(x)$ were not developed.

Statements of Inverse Problems

$$Lu = \sum_{i,j=1}^n a_{i,j}(x) u_{x_i x_j} + \sum_{j=1}^n b_j(x) u_{x_j} + c(x) u, x \in \mathbb{R}^n \quad (9)$$

$$\mu_1 |\eta|^2 \leq \sum_{i,j=1}^n a_{i,j}(x) \eta_i \eta_j \leq \mu_2 |\eta|^2, \forall x \in \mathbb{R}^n, \forall \eta \in \mathbb{R}^n; \quad (10)$$

$$\mu_1, \mu_2 = \text{const.} > 0, \quad (11)$$

$$f \in H^{s+5}(\mathbb{R}^n), a_{i,j}, b_j, c \in C^{s+3}(\mathbb{R}^n), s = \left\lceil \frac{n+1}{2} \right\rceil \quad (12)$$

Cauchy problem

$$u_{tt} = Lu, x \in \mathbb{R}^n, t \in (0, \infty), \quad (13)$$

$$u(x, 0) = f(x), u_t(x, 0) = 0. \quad (14)$$

Inverse Problem 1 (IP1, Complete Data Collection). *Assume that the function $f(x)$ is unknown. Determine this function, assuming that the following function $\varphi_1(x, t)$ is known*

$$u|_{S_\infty} = \varphi_1(x, t). \quad (15)$$

Let

$$\Omega \subset \{x_1 > 0\}, P = \{x_1 = 0\}, P_\infty = P \times (0, \infty).$$

Inverse Problem 2 (IP2, Incomplete Data Collection).

Assume that the function $f(x)$ is unknown. Determine this function, assuming that the following function $\varphi_2(x, t)$ is known

$$u|_{x \in P_\infty} = \varphi_2(x, t). \quad (16)$$

Reznickaya transform (1974)

$$\mathcal{L}u = v(x, t) = \frac{1}{\sqrt{\pi t}} \int_0^\infty \exp\left(-\frac{\tau^2}{4t}\right) u(x, \tau) d\tau.$$

$$v_t = Lv, x \in \mathbb{R}^n, t \in (0, 1), \quad (17)$$

$$v(x, 0) = f(x). \quad (18)$$

Denote

$$\mathcal{L}\varphi_1 = \bar{\varphi}_1(x, t) = v|_{S_1}, \quad \mathcal{L}\varphi_2 = \bar{\varphi}_2(x, t) = v|_{P_1}.$$

Let

$$\bar{\psi}_1(x, t) = \partial_\nu v|_{S_1}, \quad \bar{\psi}_2(x, t) = \partial_{x_1} v|_{P_1}. \quad (19)$$

We obtain

$$\begin{aligned} \|\bar{\psi}_1\|_{C^{1+\alpha, \alpha/2}(\bar{S}_1)} &\leq C \|\bar{\varphi}_1\|_{C^{2+\alpha, 1+\alpha/2}(\bar{S}_1)}, \\ \|\bar{\psi}_2\|_{C^{1+\alpha, \alpha/2}(\bar{P}_1)} &\leq C \|\bar{\varphi}_2\|_{C^{2+\alpha, 1+\alpha/2}(\bar{P}_1)}, \end{aligned}$$

1. Therefore, each problem IP1, IP2 is now replaced with the Cauchy problem for the parabolic PDE with the lateral data.
2. To estimate $f(x)$, we now can use logarithmic stability estimates of initial conditions of parabolic PDEs: Klibanov, 2006 (finite domain) and Klibanov and Tikhonravov, 2007 (infinite domain).
3. Those estimates in turn were obtained via Carleman estimates.

The data after the Reznickaya transform.

Let

$$\|\varphi_1\|_{C^4(\bar{S}_T)} \leq \delta \exp(T^2/8), \forall T > 0$$

$$\|\varphi_2\|_{C^4(\bar{P}_T)} \leq \delta \exp(T^2/8), \forall T > 0,$$

where $\delta \in (0, 1)$ is a sufficiently small number. Then

$$\|\bar{\varphi}_1\|_{H^1(\bar{S}_1)} + \|\bar{\psi}_1\|_{L_2(\bar{S}_1)} \leq C\delta, \quad (20)$$

$$\|\bar{\varphi}_2\|_{H^1(G_1)} + \|\bar{\psi}_2\|_{L_2(G_1)} \leq C\delta, \quad (21)$$

where $G \subset P$ is an arbitrary bounded domain.

Theorem 1. IP1 (complete data collection). *Assume that the upper bound C_1 of the norm $\|\nabla f\|_{L_2(\Omega)}$ is given,*

$$\|\nabla f\|_{L_2(\Omega)} \leq C_1.$$

Then there exists a constant $M_1 > 0$ and a sufficiently small number $\delta_1 \in (0, 1)$ such that if in (20) the number $\delta \in (0, \delta_1)$, then the following logarithmic stability estimate is valid

$$\|f\|_{L_2(\Omega)} \leq \frac{M_1 C_1}{\sqrt{\ln [(C_1 \delta)^{-1}]}}.$$

Theorem 2. IP2 (incomplete data collection). *Assume that the upper bound C_1 of the norm $\|f\|_{C^{2+\alpha}(\bar{\Omega})}$ be given, i.e.*

$$\|f\|_{C^{2+\alpha}(\bar{\Omega})} \leq C_2.$$

Then there exists a constant $M_2 > 0$ and a sufficiently small number $\delta_2 \in (0, 1)$ such that if the number δ in (21) is so small that $\delta \in (0, \delta_2)$, then

$$\|f\|_{L_2(\Omega)} \leq \frac{M_2 C_2}{\sqrt{\ln [(C_2 \delta)^{-1}]}}.$$

Extension to the integral inequality

These results are extended via Carleman estimates to the case of integral inequalities like, e.g.

$$\iint_{Q_1} (v_t - Lv)^2 dxdt \leq K, K = \text{const.} > 0. \quad (22)$$

We need (22) for the proof of convergence of the Quasi-Reversibility Method.

Minimize the following Tikhonov functional

$$J_{\gamma}(v) = \|v_t - Lv\|_{L^2(Q_1)}^2 + \gamma \|v\|_{H^4(Q_1)}^2,$$

subject to the boundary conditions

$$v|_{S_1} = \bar{\varphi}_1, \partial_{\nu} v|_{S_1} = \bar{\psi}_1.$$

Assume the existence of the function $F \in H^{2,1}(Q_1)$ such that

$$F|_{S_1} = \bar{\varphi}_1, \partial_{\nu} F|_{S_1} = \bar{\psi}_1.$$

Let

$$w = v - F, \tilde{F} = LF - F_t,$$
$$w|_{S_1} = \partial_\nu w|_{S_1} = 0.$$

Then

$$\bar{J}_\gamma(w) = \left\| w_t - Lw - \tilde{F} \right\|_{L_2(Q_1)}^2 + \gamma \|w\|_{H^4(Q_1)}^2 \rightarrow \min.$$

Lemma 1. For every function $\tilde{F} \in L_2(Q_1)$ and every $\gamma > 0$ there exists unique minimizer $w_\gamma = w_\gamma(\tilde{F}) \in H_0^4(Q_1)$ of the functional \bar{J}_γ . Furthermore, the following estimate holds

$$\|w_\gamma\|_{H^4(Q_1)} \leq \frac{1}{\sqrt{2\gamma}} \|\tilde{F}\|_{L_2(Q_1)}.$$

Let

$$f_\gamma(x) = w_\gamma(x, 0)$$

Let w^* be the exact solution for the exact data F^* .

Let the error estimate be

$$\left\| \tilde{F} - F^* \right\|_{L_2(Q_1)} \leq \omega.$$

Convergence Theorem. *Let $\gamma = \gamma(\omega) = \omega \in (0, 1)$. Let the function $w_{\gamma(\omega)} \in H_0^4(Q_1)$ be the unique minimizer of the functional \bar{J}_γ (Lemma 1). Let $\|w^*\|_{H^4(Q_1)} \leq Y$, where the upper estimate $Y = \text{const.} \geq 1$ is given. Then there exist a constant $M_3 > 0$ and a sufficiently small number $\omega_0 \in (0, 1)$ such that if ω is so small that $(Y^2 + 1)\omega \in (0, \omega_0)$, then the following logarithmic convergence rate is valid*

$$\|f_{\gamma(\omega)} - w^*(x, 0)\|_{L_2(\Omega)} \leq \frac{M_3 Y}{\sqrt{\ln(\omega^{-1})}}.$$

Phaseless Inverse Scattering Problems in 3-d

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$$\Delta_x u + k^2 u - q(x) u = -\delta(x - x_0), x \in \mathbb{R}^3,$$

$$u(x, x_0, k) = O\left(\frac{1}{|x - x_0|}\right), |x| \rightarrow \infty,$$

$$\sum_{j=1}^3 \frac{x_j - x_{j,0}}{|x - x_0|} \partial_{x_j} u(x, x_0, k) - iku(x, x_0, k) = o\left(\frac{1}{|x - x_0|}\right), |x| \rightarrow \infty.$$

$$q(x) \in C^2(\mathbb{R}^3), q(x) = 0 \text{ for } x \in \mathbb{R}^3 \setminus G,$$

$$q(x) \geq 0.$$

$$B_\varepsilon(y) = \{x : |x - y| < \varepsilon\}$$

Phaseless Inverse Scattering Problems in 3-d

Let $G_1 \subset \mathbb{R}^3$ be a convex bounded domain with its boundary $\partial_1 G = S \in C^1$. Let $\varepsilon \in (0, 1)$ be a number. We assume that

$$\Omega \subset G_1 \subset G, \text{dist}(S, \partial G) > 2\varepsilon \text{ and } \text{dist}(S, \partial \Omega) > 2\varepsilon.$$

Inverse Problem 3 (IP3). Suppose that the function $q(x)$ is unknown for $x \in \Omega$ and known for $x \in \mathbb{R}^3 \setminus \Omega$. Also, assume that the following function $f_1(x, x_0, k)$ is known

$$f_1(x, x_0, k) = |u(x, x_0, k)|, \forall x_0 \in S, \forall x \in B_\varepsilon(x_0), x \neq x_0, \forall k \in (a, b),$$

where $(a, b) \subset \mathbb{R}$ is an arbitrary interval. Determine the function $q(x)$ for $x \in \Omega$.

Theorem (uniqueness). *Consider IP3. Let two potentials $q_1(x)$ and $q_2(x)$ be such that $q_1(x) = q_2(x) = q(x)$ for $x \in \mathbb{R}^3 \setminus \Omega$. Let $u_1(x, x_0, k)$ and $u_2(x, x_0, k)$ be corresponding solutions of the above forward problem. Assume that*

$$|u_1(x, x_0, k)| = |u_2(x, x_0, k)|, \forall x_0 \in S, \forall x \in B_\varepsilon(x_0), x \neq x_0, \forall k \in (a, b).$$

Then $q_1(x) \equiv q_2(x)$.

- Applications in studies of reflectivity of neutrons.
- Three more phaseless inverse problems are considered in that preprint.

$$P(x) = \left| \iint_{\Omega} h(\xi) e^{ix\xi} d\xi \right|^2, x \in \mathbb{R}^n, n = 1, 2.$$

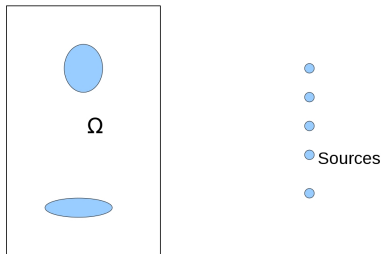
- $h(x) = A(x) \exp(i\varphi(x))$, where $A(x) = |h(x)|$
- Either $A(x)$ is known and $\varphi(x)$ is unknown, or vice versa.
- This is **Phase Retrieval Problem**. Klivanov 1985, 1987 (two papers), 2006.
- **Phaseless inverse scattering in 1-d**. Klivanov, 1989; Klivanov and Sacks, 1992. Survey: Klivanov, Sacks and Tikhonravov, 1995.

Diffusion Optical Tomography

$$\Delta u - a(\mathbf{x})u = -\delta(\mathbf{x} - \mathbf{x}_0), \mathbf{x}, \mathbf{x}_0 \in \mathbb{R}^2, \quad (23)$$

$$\lim_{|\mathbf{x}| \rightarrow \infty} u(\mathbf{x}, \mathbf{x}_0) = 0. \quad (24)$$

- $a(\mathbf{x}) = 3(\mu'_s \mu_a)(\mathbf{x})$, where μ'_s is the reduced scattering coefficient and μ_a is the absorption coefficient.



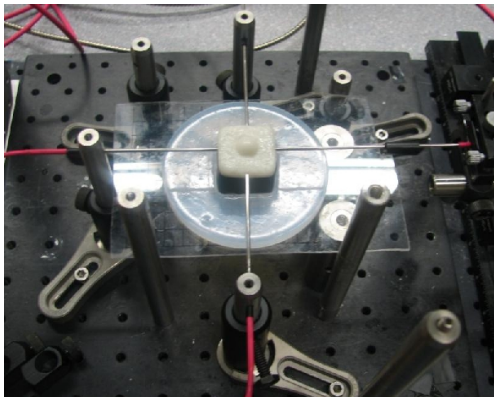
Inverse Problem. Let $k = \text{const.} > 0$ be given. Suppose that in (23) the coefficient $a(\mathbf{x})$ satisfies the following conditions

$$a \in C^1(\mathbb{R}^2), \quad a(\mathbf{x}) \geq k^2 \text{ and } a(\mathbf{x}) = k^2 \text{ for } \mathbf{x} \in \mathbb{R}^2 \setminus \Omega.$$

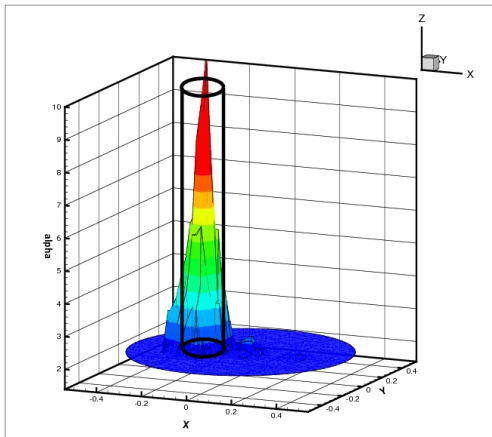
Let $L \subset (\mathbb{R}^2 \setminus \overline{\Omega})$ be a straight line and $\Gamma \subset L$ be an unbounded and connected subset of L . Determine the function $a(\mathbf{x})$ inside of the domain Ω , assuming that the constant k is given and also that the following function $\varphi(\mathbf{x}, \mathbf{x}_0)$ is given

$$u(\mathbf{x}, \mathbf{x}_0) = \varphi(\mathbf{x}, \mathbf{x}_0), \quad \forall (\mathbf{x}, \mathbf{x}_0) \in \partial\Omega \times \Gamma.$$

Diffusion Optical Tomography



Diffusion Optical Tomography



inclusion number	True contrast	Computed contrast	Relative error
1	2	2.11	5.6%
2	3	2.9	3.2%
3	4	4.22	5.7%
4	∞	6.69	unknown

Table: Computed and correct inclusion/background contrasts and the relative errors

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