

# Underwater topography “invisible” for surface waves at given frequencies

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# The invisibility.

## Approaches:

- smartly designed composite materials + special shapes (STEALTH technology)
- local deformation of space variables (HARRY POTTER'S cloak)
- *Greenleaf A., Kurylev Ya., Lassas M. Uhlmann G.* Invisibility an inverse problems. Bull. Amer. Math. Soc. 2009. V. 46.
- *Greenleaf A., Kurylev Ya., Lassas M. Uhlmann G.* Approximate quantum and acoustic cloaking. J. Spectr. Theory. 2011. V. 1.

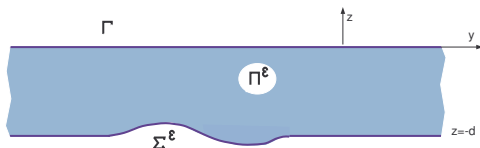
## Our approach:

- No changes in the differential equations and the boundary conditions but only design of obstacle's shape.
- The main difference is that we consider WAVEGUIDES and thus deal with a FINITE number of propagative waves.

# The linear theory of water-waves.

## The Steklov spectral problem:

- $-\Delta\varphi^\varepsilon + k^2\varphi^\varepsilon = 0$  in  $\Pi^\varepsilon$ ,
- $\partial_z\varphi^\varepsilon = \lambda\varphi^\varepsilon$  on  $\Gamma$ ,
- $\partial_\nu\varphi^\varepsilon = 0$  on  $\Sigma^\varepsilon$ ,
- $\varphi^\varepsilon$  is the velocity potential and  $\lambda^\varepsilon = g^{-1}\omega^2$  the spectral parameter with a frequency  $\omega > 0$  and the acceleration  $g > 0$  due to gravity,
- the superscript  $\varepsilon > 0$  indicates the size of the perturbation of the bottom (a warp)  
 $\Sigma^\varepsilon = \{(y, z) : y \in \mathbb{R}, z = -d + \varepsilon h(y)\}$ .



# Propagative waves.

The continuous spectrum  $[\lambda_{\dagger}, +\infty)$ .

- The cutoff point  $\lambda_{\dagger} = \lambda(k) \geq 0$  satisfies

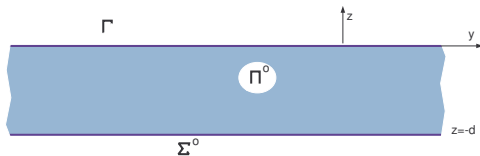
$$\lambda(m) = m \frac{1 - e^{-2md}}{1 + e^{-2md}} \text{ with } m \geq 0.$$

- If the bottom is flat, i.e.,  $h = 0$ , then, for any  $l \geq 0$ , there exists in the straight channel two propagative waves

$$w^{\pm}(y, z) = e^{\pm ily}(e^{mz} + e^{-m(z+2d)})$$

$$\text{where } m = \sqrt{k^2 + l^2}.$$

- According to the Sommerfeld principle the wave  $w^+$  travels from  $-\infty$  to  $+\infty$ .



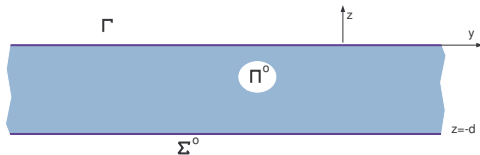
# The transmission and reflection coefficients.

## The straight channel $\Pi^0$ .

- The wave  $w^+(y, z) = e^{ily}(e^{mz} + e^{-m(z+2d)})$ , of course, travels from  $-\infty$  to  $+\infty$  without any perturbation.

## The perturbed channel $\Pi^\varepsilon$ .

- The scattered wave:  
$$u^\varepsilon(y, z) = \chi_-(y)w^+(z) + \sum_{\pm} \chi_{\pm}(y)s_{\pm}^\varepsilon w^\pm(z) + \tilde{u}^\varepsilon(y, z),$$
- where the reflection  $s_-^\varepsilon$  and transmission  $s_+^\varepsilon$  coefficients satisfy  $|s_-^\varepsilon|^2 + |s_+^\varepsilon|^2 = 1$ ,  $\tilde{u}^\varepsilon$  decays exponentially,  $\chi_{\pm}$  are cut-off functions near  $y = \pm\infty$ .



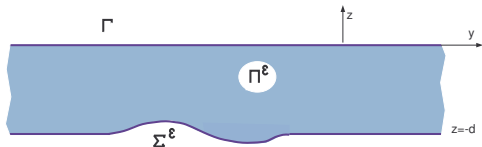
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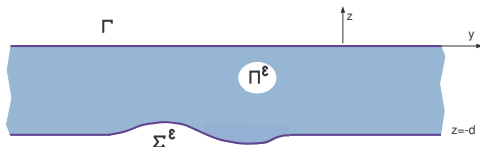


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- We fix some  $l > 0$  and the frequency  $\omega_l = \sqrt{g\lambda(k, l)^{1/2}}$ .
- The perturbation (obstacle) is “invisible” with the reflection coefficient  $s_-^\varepsilon = 0$  and transmission coefficient  $s_+^\varepsilon = 1$ .
- The perturbation (obstacle) is **non-reflective** with the reflection coefficient  $s_-^\varepsilon = 0$  (and, hence, the transmission coefficient  $s_+^\varepsilon = e^{i\psi_\varepsilon}$ ).



The “invisible” local perturbation (a warp) at a given frequency.

- One needs to find out a **smooth** profile  $h(y)$  of the slightly sloped bottom

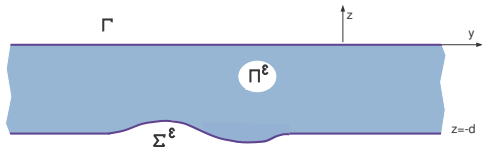
$$\Sigma^\varepsilon = \{(y, z) : y \in \mathbb{R}, z = -d + \varepsilon h(y)\}$$

( **with**  $\text{supp} h \subset (-L, +L)$ ,  $L > 0$ ) such that

$$s_-^\varepsilon = 0 \quad \text{and} \quad s_+^\varepsilon = 1$$

in the solution

$$u^\varepsilon(y, z) = \chi_-(y)w^+(z) + \sum_{\pm} \chi_{\pm}(y)s_{\pm}^\varepsilon w^{\pm}(z) + \tilde{u}^\varepsilon(y, z).$$





## The “invisible” perturbation.

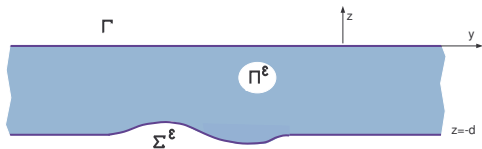
- We accept the asymptotic ansätze

$$u^\varepsilon(y, z) = w^+(y, z) + \varepsilon u'(y, z) + \dots,$$

$$s_\pm^\varepsilon = s_\pm^0 + \varepsilon s'_\pm + \dots,$$

$$\text{where } u^0(y, z) = w^+(y, z) \text{ and } s_+^0 = 1, s_-^0 = 0$$

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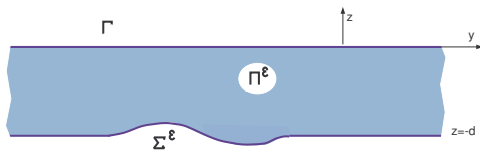
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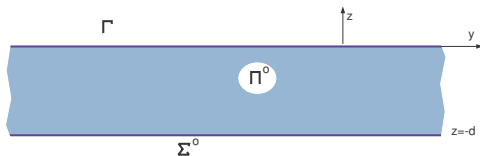
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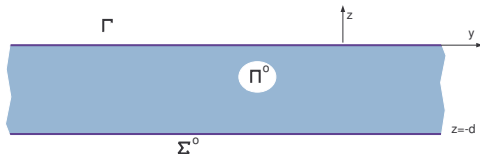
- and then rectify the bottom
- taking into account that

$$\partial_\nu = (1 + \varepsilon^2 |\partial_y h(y)|^2)^{-1/2} (-\partial_z + \varepsilon \partial_y h(y)).$$



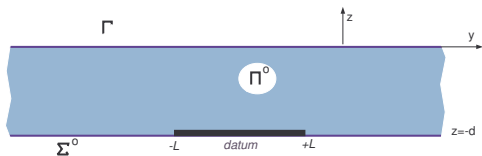
The boundary condition at the rectified bottom.

- $\partial_\nu u^\varepsilon(y, -d + \varepsilon h(y)) = -\partial_z u^0(y, -d + \varepsilon h(y)) + \varepsilon \partial_y h(y) \partial_z u^0(y, -d + \varepsilon h(y)) - \varepsilon \partial_z u'(y, -d + \varepsilon h(y)) + \dots = -\partial_z u^0(y, -d) - \varepsilon h(y) \partial_z^2 u^0(y, -d) + \varepsilon \partial_y h(y) \partial_z u^0(y, -d) - \varepsilon \partial_z u'(y, -d) + \dots$
- The Helmholtz equation provides  $\partial_z^2 u^0(y, -d) = -\partial_y^2 u^0(y, -d) + k^2 u^0(y, -d)$
- and therefore  $\partial_\nu u^\varepsilon(y, -d + \varepsilon h(y)) = \varepsilon (-\partial_z u'(y, -d) + \partial_y h(y) \partial_z u^0(y, -d) + h(y) \partial_y^2 u^0(y, -d) - h(y) k^2 u^0(y, -d)) + \dots$



The problem for the correction term.

- Thus, the function  $u'$  satisfies
$$-\Delta u'(y, z) + k^2 u'(y, z) = 0, \quad (y, z) \in \Pi^0,$$
$$\partial_z u'(y, 0) = \lambda u'(y, 0), \quad y \in \mathbb{R},$$
$$-\partial_z u'(y, -d) = -\partial_y (h(y) \partial_y u^0(y, -d)) + k^2 h(y) u^0(y, -d).$$
- There exists a unique solution such that
- $u'(y, z) = \sum_{\pm} \chi_{\pm}(y) s'_{\pm} w^{\pm}(z) + \tilde{u}'(y, z)$   
with some coefficients  $s'_{\pm}$ .



## Formulas for the coefficients.

- The correction term

$$u'(y, z) = \sum_{\pm} \chi_{\pm}(y) s'_{\pm} w^{\pm}(z) + \tilde{u}'(y, z).$$

- Insert  $u'(y, z)$  and  $w^{\pm}(y, z)$  into the Green formula in the rectangle  $(-R, R) \times (-d, 0)$  and send  $R$  to  $\infty$ .
- As a result we obtain:

$$s'_{+} = 4iN^{-1}(k^2 + l^2) \int_{-L}^L h(y) dy,$$

$$s'_{-} = 4iN^{-1}(k^2 - l^2) \int_{-L}^L e^{2ily} h(y) dy$$

with a certain  $N > 0$ .

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- Thus imposing three orthogonality conditions

$$\int_{-L}^L h(y) dy = 0, \quad \int_{-L}^L e^{2ily} h(y) dy = 0 \in \mathbb{C}$$

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- provides  $s'_{\pm} = 0$ ,
- however, we still cannot achieve  $s_{\pm}^{\varepsilon} = 0$   
because the lower-order perturbation  $\varepsilon^2 \tilde{s}_{\pm}^{\varepsilon}$ .



## Complicating the form of the profile.

- To find out an “invisible” warp we employ an idea and techniques of the **enforced stability** of embedded eigenvalues, see, e.g.,  
*Nazarov S.A.* Trapped waves in a cranked waveguide with hard walls  
**Acoustical Physics** 2011. V. 57 (6). P. 764-771,  
*Nazarov S.A.* Asymptotic expansions of eigenvalues in the continuous spectrum of a regularly perturbed quantum waveguide **Theoretical and mathematical physics** 2011. V. 167 (2). P. 606–627.
- We linearize the equations  $s_+^\varepsilon = 1$  and  $s_-^\varepsilon = 0$  around the asymptotic solution.

## Complicating the form of the profile.

- To find out an “invisible” warp we employ the techniques of the **enforced stability** of embedded eigenvalues, namely we impose the decomposition of the profile

$$h(y) = h_0(y) + \sum_{j=1}^3 \tau_j(\varepsilon) h_j(y)$$

where  $\tau = (\tau_1, \tau_2, \tau_3)$  is the vector of new small parameters and  $h_q \in C_c^4(-L, +L) \dots$

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$$\int_{-L}^L R_k(y) h_0(y) dy = 0, \quad \int_{-L}^L R_k(y) h_j(y) dy = \delta_{j,k},$$

where  $j, k = 1, 2, 3$  and

$$R_1(y) = 1, \quad R_2(y) = \cos(2ly), \quad R_3(y) = \sin(2ly)$$

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- notice that  $e^{2ily} = \cos(2ly) + i \sin(2ly)$ .

# The equations to determine the desired profile.

## Transcendental equations.

- We have  $s_{\pm}^{\varepsilon} = s_{\pm}^0 + \varepsilon s'_{\pm} + \varepsilon^2 \tilde{s}_{\pm}^{\varepsilon}$ ,  
 $s'_{+} = 4iN^{-1}(k^2 + l^2) \int_{-L}^L h(y) dy$ ,  
 $s'_{-} = 4iN^{-1}(k^2 - l^2) \int_{-L}^L e^{2ily} h(y) dy$
- Then three equations  $\text{Im}s_{+}^{\varepsilon} = 0$  and  $s_{-}^{\varepsilon} = 0 \in \mathbb{C}$  under the condition  $k \neq l$  reduce to the abstract equation  $\tau = T^{\varepsilon}(\tau)$  in  $\mathbb{R}^3$
- where  $T_1^{\varepsilon}(\tau) = -\frac{\varepsilon}{4} \frac{1}{k^2 + l^2} N \text{Im}(\tilde{s}_{+}^{\varepsilon})$ ,  $T_2^{\varepsilon}(\tau) = -\frac{\varepsilon}{4} \frac{1}{k^2 - l^2} N \text{Im}(\tilde{s}_{+}^{\varepsilon})$ ,  $T_3^{\varepsilon}(\tau) = \frac{\varepsilon}{4} \frac{1}{k^2 - l^2} N \text{Re}(\tilde{s}_{+}^{\varepsilon})$ .
- The most important point is: for a small  $\varepsilon$  **the operator  $T^{\varepsilon}$  in  $\mathbb{R}^3$  is contractive in a small ball!**

# The properties of the operator $T^\varepsilon$ .

## Estimates for the remainder.

- Rectifying the boundary: the coordinate change

$$(y, z) \mapsto (y^\varepsilon, z^\varepsilon),$$

- namely, we make the local shift near the warp

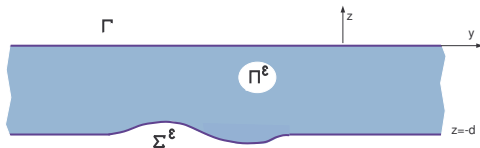
$$y^\varepsilon = y, \quad z^\varepsilon = z - \varepsilon h(y)$$

which slightly and **analytically in**  $\varepsilon$  and  $\tau$  perturbs the operators and

glue it with identity outside the vicinity of the warp.

- Profits:

the estimate  $|\tilde{s}_\pm^\varepsilon| \leq c$  in the remainder  $\tilde{s}_\pm^\varepsilon$   
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## About the warp.

- The solution  $\tau = \tau(\varepsilon)$  exists and unique in the ball  $\mathbb{B}_{\varepsilon\rho}^3$  with some  $\rho > 0$ .

- Since  $|\tau(\varepsilon)| \leq \varepsilon\rho$ , we have

$$\varepsilon h(y) = \varepsilon h_0(y) + \sum_{j=1}^3 \tau_j(\varepsilon) h_j(y) = \varepsilon h_0(y) + O(\varepsilon^2),$$

i.e.,  $h_0$  is the main term under three conditions only.

- In view of the condition  $\int_{-L}^L h_0(y) dy = 0$  (\*)  
the increment of the volume due to the warp is  $O(\varepsilon^2)$ .



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we may omit (\*) and make the volume increment  $\geq c\varepsilon$ .
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- We also do not know yet about “invisible” submerged objects.



*Thanks a lot  
for attention !*